L Number	Hits	Search Text	DB	Time stamp
4	67	((((motor engine) near4 control\$4 near3 electr\$5) and (((ampere current)	USPAT;	2004/09/10 11:06
		near2 (sensor detect\$4 meter\$4)) or amper?meter) and (battery ac dc)	US-PGPUB;	
		and ((speed velocity accelerometer) near4 (sensor detect\$4 meter\$4)))	ЕРО; ЈРО;	
		and ((torque torsion\$4 rotat\$4) near4 (sens\$4 detect\$4 meter\$4	DERWENT;	
		determin\$4 estimat\$4 asses\$4 calculat\$4)) and (torque near5 current)	IBM_TDB	
		and controller) and (motor near2 power) and (three near2 phase near2	_	
		motor )		
6	200	((((motor engine) near4 control\$4 near3 electr\$5) and (((ampere current)	USPAT;	2004/09/10 12:22
		near2 (sensor detect\$4 meter\$4)) or amper?meter) and (battery ac dc)	US-PGPUB;	
		and ((speed velocity accelerometer) near4 (sensor detect\$4 meter\$4)))	ЕРО; ЈРО;	
		and ((torque torsion\$4 rotat\$4) near4 (sens\$4 detect\$4 meter\$4	DERWENT;	
		determin\$4 estimat\$4 asses\$4 calculat\$4)) and (torque near5 current)	IBM_TDB	•
		and controller) and (motor near2 power) and (current near3 torque)		
9	7	((((motor engine) near4 control\$4 near3 electr\$5) and (((ampere current)	USPAT;	2004/09/10 12:23
		near2 (sensor detect\$4 meter\$4)) or amper?meter) and (battery ac dc)	US-PGPUB;	
		and ((speed velocity accelerometer) near4 (sensor detect\$4 meter\$4)))	ЕРО; ЛРО;	
		and ((torque torsion\$4 rotat\$4) near4 (sens\$4 detect\$4 meter\$4	DERWENT;	
		determin\$4 estimat\$4 asses\$4 calculat\$4)) and (torque near5 current)	IBM_TDB	
		and controller) and (motor near2 power) and (current near3 torque near4		
		table)		
-	23	73/862.16.ccls.	USPAT;	2004/09/08 13:26
			US-PGPUB;	
			ЕРО; ЈРО;	
			DERWENT;	
			IBM_TDB	
-	288	73/862.23.ccls.	USPAT;	2004/09/08 13:26
			US-PGPUB;	
			ЕРО; ЈРО;	
			DERWENT;	
	105	72/9/2 271-	IBM_TDB	2004/00/09 12:27
-	105	73/862.27.ccls.	USPAT;	2004/09/08 13:27
:			US-PGPUB;	
			ЕРО; ЛРО;	
			DERWENT; IBM TDB	
	103	73/862.28.ccls.	USPAT;	2004/09/08 13:27
	103	757602,26.0013.	US-PGPUB;	2004/07/08 13.27
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
_	119	73/862.29.ccls.	USPAT;	2004/09/08 13:27
	•••	75.002.25.4420.	US-PGPUB;	200 1103700 13.27
			ЕРО; ЛРО;	
			DERWENT;	
			IBM_TDB	
-	70	73/862.193.ccls.	USPĀT;	2004/09/08 13:48
			US-PGPUB;	
			ЕРО; ЈРО;	
]			DERWENT;	
			IBM_TDB	
-	4761	((motor engine) near4 control\$4) and (((ampere current) near2 (sensor	USPAT;	2004/09/08 14:00
		detect\$4 meter\$4)) or amper?meter) and (battery ac dc) and ((speed	US-PGPUB;	
		velocity accelerometer) near4 (sensor detect\$4 meter\$4))	ЕРО; ЈРО;	
			DERWENT,	
			IBM_TDB	
-	2749	(((motor engine) near4 control\$4) and (((ampere current) near2 (sensor	USPAT;	2004/09/09 10:38
		detect\$4 meter\$4)) or amper?meter) and (battery ac dc) and ((speed	US-PGPUB;	
		velocity accelerometer) near4 (sensor detect\$4 meter\$4))) and ((torque	ЕРО; ЛРО;	
		torsion\$4 rotat\$4) near4 (sens\$4 detect\$4 meter\$4 determin\$4	DERWENT;	
		estimat\$4 asses\$4 calculat\$4))	IBM_TDB	

-	4	("5543695" "5670856").pn.	USPAT;	2004/09/08 14:07
		(35/35/3 55/3535 ),p.i.	US-PGPUB;	200 11 051 00 1 11.07
			ЕРО; ЛРО;	
			DERWENT;	
			IBM TDB	
	1263	(((motor engine) near4 control\$4) and (((ampere current) near2 (sensor	USPAT;	2004/09/09 10:40
		detect\$4 meter\$4)) or amper?meter) and (battery ac dc) and ((speed	US-PGPUB;	
		velocity accelerometer) near4 (sensor detect\$4 meter\$4))) and ((torque	EPO; JPO;	
	1	torsion\$4 rotat\$4) near4 (sens\$4 detect\$4 meter\$4 determin\$4	DERWENT;	
	1	estimat\$4 asses\$4 calculat\$4)) and (torque near5 current)	IBM TDB	
_	30	((((motor engine) near4 control\$4) and (((ampere current) near2 (sensor	USPAT;	2004/09/09 10:41
		detect\$4 meter\$4)) or amper?meter) and (battery ac dc) and ((speed	US-PGPUB;	
		velocity accelerometer) near4 (sensor detect\$4 meter\$4))) and ((torque	EPO; JPO;	
		torsion\$4 rotat\$4) near4 (sens\$4 detect\$4 meter\$4 determin\$4	DERWENT;	
		estimat\$4 asses\$4 calculat\$4)) and (torque near5 current)).clm.	IBM TDB	
-	594	(((motor engine) near4 control\$4 near3 electr\$5) and (((ampere current)	USPĀT;	2004/09/09 10:48
		near2 (sensor detect\$4 meter\$4)) or amper?meter) and (battery ac dc)	US-PGPUB;	
		and ((speed velocity accelerometer) near4 (sensor detect\$4 meter\$4)))	ЕРО; ЛРО;	
		and ((torque torsion\$4 rotat\$4) near4 (sens\$4 detect\$4 meter\$4	DERWENT;	
		determin\$4 estimat\$4 asses\$4 calculat\$4)) and (torque near5 current)	IBM_TDB	
-	385	(((motor engine) near4 control\$4 near3 electr\$5) and (((ampere current)	USPAT;	2004/09/09 13:22
		near2 (sensor detect\$4 meter\$4)) or amper?meter) and (battery ac dc)	US-PGPUB;	
		and ((speed velocity accelerometer) near4 (sensor detect\$4 meter\$4)))	ЕРО; ЛРО;	
		and ((torque torsion\$4 rotat\$4) near4 (sens\$4 detect\$4 meter\$4	DERWENT;	
		determin\$4 estimat\$4 asses\$4 calculat\$4)) and (torque near5 current)	IBM_TDB	
		and controller		
-	42	((((motor engine) near4 control\$4 near3 electr\$5) and (((ampere current)	USPAT;	2004/09/09 14:30
		near2 (sensor detect\$4 meter\$4)) or amper?meter) and (battery ac dc)	US-PGPUB;	
		and ((speed velocity accelerometer) near4 (sensor detect\$4 meter\$4)))	ЕРО; ЈРО;	
		and ((torque torsion\$4 rotat\$4) near4 (sens\$4 detect\$4 meter\$4	DERWENT;	
		determin\$4 estimat\$4 asses\$4 calculat\$4)) and (torque near5 current)	IBM_TDB	
	ł	and controller) and (electr\$4 near2 load)		
-	261	((((motor engine) near4 control\$4 near3 electr\$5) and (((ampere current)	USPAT;	2004/09/10 10:03
		near2 (sensor detect\$4 meter\$4)) or amper?meter) and (battery ac dc)	US-PGPUB;	
		and ((speed velocity accelerometer) near4 (sensor detect\$4 meter\$4)))	ЕРО; ЈРО;	
		and ((torque torsion\$4 rotat\$4) near4 (sens\$4 detect\$4 meter\$4	DERWENT;	
	ļ	determin\$4 estimat\$4 asses\$4 calculat\$4)) and (torque near5 current)	IBM_TDB	
		and controller) and (motor near2 power)	LICDAT	2004/00/10 12:21
-	65	((((motor engine) near4 control\$4 near3 electr\$5) and (((ampere current)	USPAT;	2004/09/10 12:21
		near2 (sensor detect\$4 meter\$4)) or amper?meter) and (battery ac dc)	US-PGPUB;	
		and ((speed velocity accelerometer) near4 (sensor detect\$4 meter\$4)))	EPO; JPO;	
		and ((torque torsion\$4 rotat\$4) near4 (sens\$4 detect\$4 meter\$4	DERWENT;	
		determin\$4 estimat\$4 asses\$4 calculat\$4)) and (torque near5 current) and controller) and (motor near2 power) and (compar\$4 near3 torque)	IBM_TDB	
	<u></u>	and controller) and (motor hearz power) and (compars 4 hears torque)	L <u></u>	l